

(前回) \vec{B} finite,

\vec{L}
 \downarrow
 circular motion
 \sim magnetization
 円運動
 磁化.

$$\Delta E \sim -\frac{e}{2m} \vec{L} \cdot \vec{B}$$

orbital magnetization
軌道磁化.

To be consistent with exp., $\vec{L} \rightarrow \vec{L} + g\vec{S}$ ($g \sim 2$)

$$\vec{S}: [S_i, S_j] = i\hbar \epsilon_{ijk} S_k, \quad \vec{S}^\dagger = \vec{S}$$

$$S^2 = \hbar^2 s(s+1), \quad s = 1/2 \quad \rightarrow \text{spin}$$

★ spin and Pauli matrix (1,0,1)行列.

$$\vec{S}^2 |s, m\rangle = \hbar^2 s(s+1) |s, m\rangle \quad (s = 1/2)$$

$$S_z |s, m\rangle = \hbar M |s, m\rangle, \quad M = -s, \dots, s = -1/2, 1/2$$

$$\langle j, m+1 | J_+ | j, m \rangle = \hbar \sqrt{(j-m)(j+m+1)} \quad (*1)$$

$$\langle j, m-1 | J_- | j, m \rangle = \hbar \sqrt{(j+m)(j-m+1)} \quad (*2)$$

$$\begin{cases} M = +1/2, \uparrow \\ M = -1/2, \downarrow \end{cases} \quad \text{として.}$$

$$(*1) \rightarrow \langle \uparrow | S_+ | \downarrow \rangle = \hbar \sqrt{(\frac{1}{2} - (-\frac{1}{2}))(\frac{1}{2} - (-\frac{1}{2}) + 1)} = \hbar, \quad S_+ | \uparrow \rangle = 0$$

($j = 1/2, m = -1/2$)

$$(*2) \rightarrow \langle \downarrow | S_- | \uparrow \rangle = \hbar \sqrt{(\frac{1}{2} + \frac{1}{2})(\frac{1}{2} - \frac{1}{2} + 1)} = \hbar, \quad S_- | \downarrow \rangle = 0$$

($j = 1/2, m = 1/2$)

$$S_z | \uparrow \rangle = \hbar M | \uparrow \rangle = \frac{\hbar}{2} | \uparrow \rangle \quad (M = 1/2)$$

$$S_z | \downarrow \rangle = \hbar M | \downarrow \rangle = -\frac{\hbar}{2} | \downarrow \rangle \quad (M = -1/2)$$

これを行列表示

$$\begin{pmatrix} \langle \uparrow | \\ \langle \downarrow | \end{pmatrix} S_z \begin{pmatrix} | \uparrow \rangle \\ | \downarrow \rangle \end{pmatrix} = \begin{pmatrix} \langle \uparrow | S_z | \uparrow \rangle & \langle \uparrow | S_z | \downarrow \rangle \\ \langle \downarrow | S_z | \uparrow \rangle & \langle \downarrow | S_z | \downarrow \rangle \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \equiv \frac{\hbar}{2} \sigma_z$$

$$\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (\text{one of}) \text{ the Pauli matrix}$$

$$\therefore S_z = \frac{\hbar}{2} \sigma_z$$

$$\vec{S} = \frac{\hbar}{2} \vec{\sigma}, \quad S_x = \frac{\hbar}{2} \sigma_x, \quad S_y = \frac{\hbar}{2} \sigma_y$$

$$S_{\pm} = S_x \pm iS_y \rightarrow \begin{cases} S_x = \frac{1}{2}(S_+ + S_-) \\ S_y = \frac{1}{2i}(S_+ - S_-) \end{cases}$$

$$\begin{pmatrix} \langle \uparrow | \\ \langle \downarrow | \end{pmatrix} S_{\pm} \begin{pmatrix} | \uparrow \rangle \\ | \downarrow \rangle \end{pmatrix} = \begin{pmatrix} \langle \uparrow | S_x | \downarrow \rangle & \langle \uparrow | S_x | \uparrow \rangle \\ \langle \downarrow | S_x | \uparrow \rangle & \langle \downarrow | S_x | \downarrow \rangle \end{pmatrix}$$

$$(\langle \uparrow | \downarrow \rangle = \langle 1/2 | -1/2 \rangle = 0, \quad \langle \downarrow | \uparrow \rangle = 0)$$

$$= \begin{cases} \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} & (S_+) \\ \hbar \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} & (S_-) \end{cases}$$

$$\rightarrow S_x = \frac{1}{2}(S_+ + S_-) = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{\hbar}{2} \sigma_x$$

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$S_y = \frac{1}{2i}(S_+ - S_-) = \frac{\hbar}{2i} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \frac{\hbar}{2} \sigma_y$$

$$\sigma_y = \frac{1}{i} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

Pauli matrix

$$\vec{\sigma} = \begin{pmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \end{pmatrix}$$

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Vector of matrices

~ 基本的性質 ~

$$\sigma_x^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = E_2 \quad 2 \times 2 \text{ unit matrix}$$

$$\sigma_y^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} -i \cdot i & 0 \\ 0 & i \cdot (-i) \end{pmatrix} = E_2$$

$$\sigma_z^2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = E_2$$

$$\therefore \sigma_i^2 = E_2$$

$$\sigma_x \sigma_y = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = i \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = i \sigma_z$$

$$\sigma_y \sigma_z = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} = i \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = i \sigma_x$$

$$\sigma_z \sigma_x = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = i \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = i \sigma_y$$

C.P. cyclic permutation 循環置換



$$\sigma_x^\dagger = \sigma_x, \quad \sigma_y^\dagger = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}^* = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \sigma_y, \quad \sigma_z^\dagger = \sigma_z$$

$$\vec{\sigma}^\dagger = \vec{\sigma}$$

$\vec{\sigma}$: hermite

$$\begin{pmatrix} (\sigma_x \sigma_y)^\dagger = (i \sigma_z)^\dagger \\ \sigma_y^\dagger \sigma_x^\dagger = -i \sigma_z^\dagger \\ \sigma_y \sigma_x = -i \sigma_z \end{pmatrix} \rightarrow \sigma_i \sigma_j = -\sigma_j \sigma_i \quad (i \neq j)$$

$\sigma_i = E_2$ で表わされる.

$$(i \neq j) \quad \sigma_i \sigma_j = i \epsilon_{ijk} \sigma_k$$

$$\begin{pmatrix} \text{Tr } \sigma_x = 0 \\ \text{Tr } \sigma_y = 0 \\ \text{Tr } \sigma_z = 0 \end{pmatrix} \rightarrow \text{Tr } \vec{\sigma} = \vec{0}$$

$$\{\sigma_i, \sigma_j\} = \sigma_i \sigma_j + \sigma_j \sigma_i = \begin{cases} E_2 + E_2 = 2E_2 & i=j \\ 0 & i \neq j \end{cases} \quad \therefore \{\sigma_i, \sigma_j\} = 2\delta_{ij} E_2$$

For a generic 2×2 matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$,

(notation $E_2 \equiv \sigma_0 \rightarrow \sigma_x = \sigma_1, \sigma_y = \sigma_2, \sigma_z = \sigma_3$) \uparrow 4 real numbers a, b, c, d
対応するはず..

$$A = A_0 \sigma_0 + A_1 \sigma_1 + A_2 \sigma_2 + A_3 \sigma_3 \quad A_1, A_2, A_3, A_4, \dots$$

$$A = \sum_{i=0}^3 A_i \sigma_i$$

$$\text{Tr } A \sigma_0 = \text{Tr } A = \sum_{i=0}^3 \text{Tr} (A_0 \sigma_0^2 + A_1 \underbrace{\sigma_1 \sigma_0}_{\sigma_1} + A_2 \underbrace{\sigma_2 \sigma_0}_{\sigma_2} + A_3 \underbrace{\sigma_3 \sigma_0}_{\sigma_3}) = A_0 \text{Tr } \sigma_0 = 2A_0$$

$$\text{Tr } A_1 \sigma_1 = \sum_{i=0}^3 \text{Tr} (A_0 \sigma_0 \sigma_1 + A_1 \underbrace{\sigma_1^2}_{\sigma_1} + A_2 \underbrace{\sigma_2 \sigma_1}_{-i \sigma_3} + A_3 \underbrace{\sigma_3 \sigma_1}_{i \sigma_2}) = A_1 \text{Tr } \sigma_1 = 2A_1$$

$$\rightarrow \begin{cases} A_1 = \frac{1}{2} \text{Tr } A \sigma_1 \\ A_2 = \frac{1}{2} \text{Tr } A \sigma_2 \\ A_3 = \frac{1}{2} \text{Tr } A \sigma_3 \end{cases}$$

$$A = A_0 \sigma_0 + A_1 \sigma_1 + A_2 \sigma_2 + A_3 \sigma_3 = A_0 \sigma_0 + \vec{A} \cdot \vec{\sigma} \quad \vec{A} = \begin{pmatrix} A_1 \\ A_2 \\ A_3 \end{pmatrix}$$

$$A_i = \frac{1}{2} \text{Tr } A \sigma_i \quad i = 0, 1, 2, 3$$

$$\begin{aligned} \vec{A} \cdot \vec{\sigma} &= A_1 \sigma_1 + A_2 \sigma_2 + A_3 \sigma_3 \\ &= A_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + A_2 \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + A_3 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} A_3 & A_1 - iA_2 \\ A_1 + iA_2 & -A_3 \end{pmatrix} \end{aligned}$$

$$A_0 = \text{Tr } A$$

\rightarrow if $\text{Tr } A = 0$, $A = \vec{A} \cdot \vec{\sigma}$ とする $\exists \vec{A}$ $A^\dagger = A$, $\vec{A} = \text{real}$ ($\vec{\sigma}^\dagger = \vec{\sigma}$)

$A, B : 2 \times 2$ matrix

$$A = (\vec{A} \cdot \vec{\sigma}) \quad , \quad B = (\vec{B} \cdot \vec{\sigma})$$

$$A \cdot B = (\vec{A} \cdot \vec{\sigma})(\vec{B} \cdot \vec{\sigma}) = \vec{A} \cdot \vec{B} \sigma_0 + i \vec{\sigma} \cdot (\vec{A} \times \vec{B}) \quad \text{(Dirac) formula}$$

product of the matrices 行列の積

$$\begin{aligned} (\because) (\vec{A} \cdot \vec{\sigma})(\vec{B} \cdot \vec{\sigma}) &= A_i \sigma_i B_j \sigma_j \quad i=1 \sim 3, j=1 \sim 3, \\ &= A_i B_j \sigma_i \sigma_j \\ &= \sum_{i=j} A_i B_i \sigma_i^2 + \sum_{i \neq j} A_i B_j \sigma_i \sigma_j \quad i \epsilon_{ijk} \sigma_k \\ &= \sum_{i=0}^3 A_i B_i \sigma_0 + \sum_{i,j,k} \frac{A_i B_j i \epsilon_{ijk}}{i(A \times B)_k} \sigma_k \\ &= (\vec{A} \cdot \vec{B}) \sigma_0 + i \vec{\sigma} \cdot (\vec{A} \times \vec{B}) \quad \square \end{aligned}$$

ex)

$$H = -\mu \frac{\vec{S} \cdot \vec{B}}{\hbar} \quad \text{の固有値は?}$$

$\vec{B} \parallel \vec{z}$ scalar

$$H = -\mu \frac{\sigma_z B}{2 \hbar} = -\frac{\mu B \hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} -\frac{\hbar}{2} \mu B & 0 \\ 0 & \frac{\hbar}{2} \mu B \end{pmatrix} \rightarrow \pm \frac{1}{2} \hbar \mu B.$$

another way

$$\text{Tr } H = -\mu \text{Tr } \vec{S} \cdot \vec{B} = -\mu \hbar \vec{B} \cdot \text{Tr } \vec{\sigma} = 0$$

eigen value E_1, E_2

$$\text{Tr } H = E_1 + E_2 = 0 \quad E_2 = -E_1$$

$$\begin{aligned} H^2 &= \left(\frac{\mu \hbar}{2} \vec{B} \cdot \vec{\sigma} \right)^2 = \left(\frac{\mu \hbar}{2} \right)^2 (\vec{B} \cdot \vec{\sigma})(\vec{B} \cdot \vec{\sigma}) \\ &= \left(\frac{\mu \hbar}{2} \right)^2 (\vec{B} \cdot \vec{B} \sigma_0 + i \vec{\sigma} \cdot \vec{B} \times \vec{B}) \\ &= \left(\frac{\mu \hbar}{2} \right)^2 |\vec{B}|^2 \sigma_0 \quad E_1 = \frac{\mu \hbar}{2} |\vec{B}| \quad \square \end{aligned}$$

★ Time reversal symmetry 時間反轉对称性

symmetry operation 对称操作 \longleftrightarrow unitary operator

Time reversal \longleftrightarrow anti-unitary operation

$$\Theta = \underbrace{i\sigma_2}_{\text{unitary}} K \quad \leftarrow \text{complex conjugate} \quad = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} K \quad U\sigma_2 = i \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$(i\sigma_2)^\dagger = -i\sigma_2^\dagger = -i\sigma_2$$

$$(i\sigma_2)^\dagger i\sigma_2 = (-i\sigma_2)(i\sigma_2) = \sigma_2^2 = E_2. \quad i\sigma_2 : \text{unitary}$$

Θ : time reversal operator

$$\Theta \sigma_1 \Theta^{-1} = i\sigma_2 (\sigma_1)^* (-i\sigma_2) = \sigma_2 \sigma_1^* \sigma_2 = \sigma_2 \sigma_1 \sigma_2 = i\sigma_2 \sigma_3 = i^2 \sigma_1 = -\sigma_1$$

$$\Theta \sigma_2 \Theta^{-1} = i\sigma_2 (\sigma_2)^* (-i\sigma_2) = \sigma_2 \sigma_2^* \sigma_2 = -\sigma_2^3 = -\sigma_2$$

$$\Theta \sigma_3 \Theta^{-1} = i\sigma_2 (\sigma_3)^* (-i\sigma_2) = \sigma_2 \sigma_3^* \sigma_2 = \sigma_2 \sigma_3 \sigma_2 = i\sigma_1 \sigma_2 = i^2 \sigma_3 = -\sigma_3$$

$$\Theta \vec{\sigma} \Theta^{-1} = -\vec{\sigma}$$

$$\Theta \vec{S} \Theta^{-1} = -\vec{S}$$

$$\text{cf) } \vec{L} = \vec{r} \times \vec{p}$$

$$\Theta \vec{r} \Theta^{-1} = \vec{r}$$

$$\Theta \vec{p} \Theta^{-1} = \Theta \frac{\hbar}{i} \nabla \Theta^{-1} = -\vec{p}$$

$$\Theta \vec{L} \Theta^{-1} = -\vec{L}$$

$$\Theta \vec{L} \cdot \vec{S} \Theta^{-1} = (-\vec{L}) \cdot (-\vec{S}) = \vec{L} \cdot \vec{S}$$

spin orbit interaction invariant

Θ invariant